IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

Applicant:

Adam C. Braun, et al.

Serial No.:

Unassigned

Filing Date:

September 9, 2003

For:

POSITION SENSING METHODS FOR

INTERFACE DEVICES

Examiner:

Unassigned

Art Unit:

2673

Mail Stop: Patent Application Commissioner for Patents

P.O. Box 1450

Alexandria, VA 22313-1450

Sir:

INFORMATION DISCLOSURE STATEMENT

Pursuant to 37 C.F.R. §§ 1.56, 1.97, and 1.98, Applicants submit herewith on Form PTO-1449 a listing of documents submitted in the parent application. Applicants respectfully request consideration of the cited documents and making the same of record in the prosecution of the above-identified application. In so doing, Applicants do not waive any rights to take appropriate action to establish patentability over the listed documents should they be applied as references against the claims of the present application.

This Information Disclosure Statement is being submitted with the application, and, therefore, no certification or fee is required (37 C.F.R. § 1.97b(1)). However, should any fees be due, the Commissioner is authorized to charge such fees to Deposit Account No. 16-1435. A duplicate of this sheet is attached for that purpose.

Date: September 9, 2003

John C. Alemanni Reg. No. 47,384

Respectfully submitted,

KILPATRICK STOCKTON LLP 1001 West Fourth Street Winston-Salem, North Carolina 27101-2400 (336) 607-7300

Form 1449 (Modified)	Atty Docket No. IMM1P050A	Applic. No.: 09/571,397
Information Disclosure Statement By Applicant	Applicant: Martin et al. Filing Date: 5/15/00	Group 2673
(Use Several Sheets if Necessary)		

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Examiner					1	Sub-	Filing
Initial	No.	Patent No.	Date	Patentee	Class	class	Date
	A	3,490,059	1/13/70	Paulsen et al.	73	133	6/6/66
	В	3,903,614	9/9/75	Diamond et al.	35	12S	3/27/70
	$\frac{\tilde{c}}{c}$	3,919,691	11/11/75	Noll	340	172.5	5/26/71
<u> </u>	D	4,148,014	4/3/79	Burson	340	709	4/6/77
	E	4,227,319	10/14/80	Guy et al.	35	12S	3/5/79
<u> </u>	F	4,398,889	8/16/83	Lam et al.	434	45	6/8/81
	G	4,477,043	10/16/84	Repperger	244	223	10/16/84
	H	4,560,983	12/24/85	Williams	340	825	9/17/82
ļ	T	4,603,284	7/29/86	Perzley	318	568	6/5/84
	1 T	4,632,341	12/30/86	Repperger et al.	244	230	2/6/85
	K	4,677,355	6/30/87	Baumann	318	160	5/27/86

Foreign Patent or Published Foreign Patent Application

Examiner		Document	Publication	Country or		Sub-	Trans	slation
Initial	No.	No.	Date	Patent Office	Class	class	Yes	No
	L	0 085 518	8/10/83	EPO			X	
	M	0 111 992	6/27/84	EPO		<u> </u>	X	<u> </u>
	N	0470257A1	12.02.92	EPO			X	
	0	0655301A1	31.05.95	EPO			X	ļ
	P	WO9520788	03.08.95	PCT		<u> </u>	X	<u> </u>

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Initial	No.	Author, Title, Date, Place (e.g. Journal) of Publication			
	R	Frederick P. Brooks, Jr. et al., "Project GROPE-Haptic Displays for Scientific Visualization," Computer Graphics, Vol. 24 # 4, Aug. 1990, pp. 177-185.			
	}	Louis Rosenberg, "A Force Feedback Programming Primer," Immersion Corporation, 1997, pp. 1-176.			
	T	Patrick Fischer et al., "Specification and Design of Input Devices for Feleoperation," IEEE CH2876-1, 1990, pp. 540-545.			
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	A	4,734,685	3/29/88	Watanabe	340	710	7/18/84
	В	4,775,289	10/4/88	Kazerooni	414	735	9/25/87
	C	4,795,296	1/3/89	Jau	414	5	11/17/86
	D	4,800,721	1/31/89	Cemenska et al.	60	393	2/13/87
	E	4,811,608	3/14/89	Hilton	73	862.04	11/6/86
	F	4,815,006	3/89	Andersson et al.	395	89	
	G	4,819,195	4/4/89	Bell et al.	364	571.05	1/20/87
	H	4,823,634	4/25/89	Culver.	74	471 XY	11/3/87
	I	4,840,634	6/89	Muller et al.	623	24	
	 	4,868,549	9/19/89	Affinito et al.	340	710	5/18/87
	K	4,914,976	4/10/90	Wyllie ·	74	523	4/13/88

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	L	0875819	Nov 11 98	EPO			X	
	M	WO9532459	11/30/95	PCT			X	
	N	0470257A1	Feb 12 92	EPO			X	
	0	0655301A1	May 31 95	EPO			X	
	P	0626634A2	Nov 30 94	EPO			X	

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Initial	No.	Author, Title, Date, Place (e.g. Journal) of Publication					
	R	J. Edward Colgate et al., "Implementation of Stiff Virtual Walls in Force-					
		reflecting Interfaces," Dept. of Mechanical Engineering, Northwestern					
		Univ., Evanston IL. 1993, pp. 1-7.					
	S	Antal K. Bejczy et al., "The Phantom Robot: Predictive Displays for					
		Teleoperation with Time Display," IEEE CH2876-1, 1990, pp. 546-550.					
	T	Louis B. Rosenberg, "The Use of Virtual Fixtures as Perceptual Overlays to					
		Enhance Operator Performance in Remote Environments" Crew Systems					
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		AFB OH 45433-7901, 1992, pp. 1-42.					
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IIItiai	A A	4,935,728	6/19/90	Kley	340	709	11/20/87	
	B	4,961,038	10/2/90	MacMinn	318	696	10/16/89	
	$\frac{1}{C}$	4,962,448	10/9/90	DeMaio et al.	364	146	9/30/88	
	$\frac{D}{D}$	4,982,504	1/8/91	Soderberg et al.	33	502	2/17/89	
<u>.</u>	E	4,983,901	1/8/91	Lehmer	318	685	4/21/89	
	$\frac{D}{F}$	5,007,300	4/16/91	Siva	74	471 XY	1/22/90	
	G	5,044,956	9/3/91	Behensky et al.	434	45	1/12/89	
	H	5,076,517	12/31/91	Ferranti et al.	244	228	8/14/89	
	T	5,107,080	4/92	Rosen	200	6A		
·	+	5,116,051	5/26/92	Moncrief et al.	273	448 B	6/8/90	
	K	5,116,180	5/92	Fung et al.	414	5		

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Hittai	A	5,125,261	6/30/92	Powley	73	1J	5/28/91
	B	5,142,931	9/1/92	Menahem	74	471 XY	2/14/91
	C	5,143,505	9/1/92	Burdea et al.	414	5	2/26/91
	$\frac{\cup}{D}$	5,146,566	9/8/92	Hollis Jr. et al.	395	275	5/29/91
	E	5,148,377	9/15/92	McDonald	364	560	6/12/89
·	F	5,156,363	10/20/92	Cizewski et al.	244	223	2/28/91
	G	5,182,557	1/93	Lang	341	20	
	H	5,184,319	2/2/93	Kramer	364	806	2/2/90
·	11 T	5,185,561	2/9/93	Good et al.	318	432	7/23/91
	+ +	5,193,963	3/16/93	McAffee et al.	414	5	10/31/90
	K	5.195,179	3/16/93	Tokunaga	395	161	5/21/90

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• .	-	interfaces", Dept. Of Mech Engineering, MIT, 1994, pp. 1-11.					
	S	etsuo Kotoku, "A Predictive Display with Force Feedback and its pplication to Remote Manipulation System with Transmission Time					
		Delay", IEEE 0-7803-0737-2, 1992, pp. 239-246.					
	T	Louis B. Rosenberg et al., "The use of force feedback to enhance graphical ser interfaces," Stereoscopic Displays and Virtual Reality Systems, Proc. SPIE 2653, 19, 1996, pp. 243-248.					
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HIIIIai ·	A A	5,204,600	4/20/93	Kahkoska	318	602	2/6/91	
	В	5,206,930	4/27/93	Ishikawa et al.	395	95	2/7/92	
	C	5,209,131	5/11/93	Baxter	73	865.8	10/12/90	
	D	5,220,260	6/15/93	Schuler	318	561	10/24/91	
	E	5,223,776	6/93	Radke et al.	318	568.1		
	F	5,228,356	7/20/93	Chuang	74	471	11/25/91	
	G	5,230,623	7/27/93	Guthrie et al.	433	72	12/10/91	
	H	5,235,868	8/17/93	Culver	74	471 XY	10/2/91	
	11 T	5,239,246	8/24/93	Kim	318	568	7/8/92	
	1 T	5,254,919	10/19/93	Bridges et al.	318	560	3/22/91	
	K	5.264.768	11/23/93	Gregory et al.	318	561	10/6/92	

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	R	ernard D. Adelstein et al., "Design and Implementation of a Force effecting Manipulandum for Manual Control Research" NASA Ames esearch/Dept. of Mechanical Engineering, MIT, 1992, pp. 1-24.				
	S	Pietro Buttolo et al., "Pen-based Force Display for Precision Manipulation in Virtual Environments", IEEE 0-8186-7084-3, 1995, pp. 217-224.				
	T	Brain Schmult et al., "Application Areas for a Force-feedback Joystick", DSC-Vol. 49, Advances in Robotics, Mechatronics, and Haptic Interfaces, 1993, pp. 47-54.				
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Information Disclosure Statement By Applicant	Applicant: Martin et al. Filing Date: 5/15/00	Group 2673
(Ties Coveral Sheets if Necessary)		

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Examiner Initial	No.	Patent No.	Date	Patentee	Class	class	Date
muai	NO.	5,286,203	2/15/94	Fuller et al.	434	45	10/7/92
	$\frac{A}{B}$	5,296,846	3/22/94	Ledley	345	161	10/5/92
	$\frac{1}{c}$	5,296,871	3/22/94	Paley	345	163	7/27/92
	D	5,327,790	7/12/94	Levin et al.	. 73	862.325	6/19/92
•	E	5,341,459	8/23/94	Backes	395	95	8/9/91
	F	5,355,148	10/11/94	Anderson	345	166	1/14/93
	G	5,374,942	12/20/94	Gilligan et al.	345	157	8/12/93
	H	5,389,865	2/14/95	Jacobus et al.	318	568.11	12/2/92
	 	5,396,266	3/7/95	Brimhall	345	161	6/8/93
	十	5,398,044	3/14/95	Hill	345	145	12/7/93
	K	5,402,582	4/4/95	Raab	33	503	2/23/93

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	R	S.C. Jacobson et al. "High Performance, High Dexterity, Force Reflective				
		Teloperator II', ANS Topical Meeting on Robotics and Remote Systems,				
		1991, pp. 1-10.				
	S	Margaret Minsky et al "Feeling and Seeing: Issues in Force Display",				
Ì		Dept. of Computer Science, University of NC at Chapel Hill, ACM 1990				
·	٠,	089791-351-5, pp. 235-242, 270.				
		089/91-331-3, pp. 233-242, 270.				
	T	Koichi Hirota et al., "Development of Surface Display", IEEE 0-7803-1363-				
		1, 1993, pp. 256-262.				
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Information Disclosure Statement By Applicant	Martin et al. Filing Date: 5/15/00	Group 2673
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Examiner	T			· ·	Į	Sub-	Filing
Initial	No.	Patent No.	Date	Patentee	Class	class	Date
Hittai	A A	5,405,152	4/11/95	Katanics et al.	273	438	6/8/93
	B	5,414,337	5/9/95	Schuler	318	561	6/11/93
	$\frac{1}{c}$	5,473,235	12/5/95	Lance et al.	318	561	.12/21/93
	$\frac{1}{D}$	5,477,237	12/19/95	Parks	345	156	7/14/94
	E	5,482,051	1/96	Reddy et al.	128	733	
	F	5,512,919	4/30/96	Araki	345	156	03/30/93
	G	5,513,100	4/30/96	Parker et al.	364	167.01	06/10/93
	H	5,551,701	9/3/96	Bouton et al.	463	36 -	1/5/94
	117	5,570,111	10/29/96	Barrett et al.	345	157	10/3/94
	++	5,576,727	11/19/96	Rosenberg et al.	345	179	06/05/95
	K	5,587,937	12/24/96	Massie et al.	364	578	4/25/95

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		Input/output Device", Dept. of Electrical Engineering, University of British
		Columbia, Vancouver, BC, 1993, pp. 1-27.
	S	Hiroo Iwata, "Aritificial Reality with Force-feedback: Development of
		Desktop Virtual Space with Compact Master Manipulator", ACM 0-89791-
1		344-2, 1990, pp. 165-170.
	Т	Vincent Hayward et al. "Design and Multi-Objective Optimization of a
	1	Linkage for a Haptic Interface," Advances in Robot Kinematics and
Ì		Computationed Geometry, Kluwer Academic Publishers, 1994, pp. 359-368.
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<u>·</u>	$\frac{11}{B}$	5,589,854	12/96	Tsai	345	161	
	1. C	5,591,082	1/7/97	Jensen et al.	463	38	1/5/95
	D	5,611,731	3/18/97	Bouton et al.	463	37	9/8/95
	E	5,623,582	4/97	Rosenberg	395	99 .	
	$+\frac{D}{F}$	5,629,594	5/13/97	Jacobus et al.	318	568.11	10/16/95
	+ G	5,642,469	06/24/97	Hannaford et al.	395	99	11/03/94
	H	5,643,087	7/97	Marcus et al.	463	38	
	II	5,656,901	8/12/97	Kurita	318	436	4/21/95
	T	5,666,138	09/09/97	Culver	345	161	11/22/94
	K	5,680,141	10/97	Didomenico et al.	342	372	

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	S	Winey III, Calvin, "Computer Simulated Visual and Tactile Feedback as an Aid to Manipulator and Vehicle Control," Dept. of Mech. Engineering, MIT, 1981, pp. 1-79.
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Group 2673

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	A	5,694,153	12/97	Aoyagi et al.			8/1/96
	В	5,709,219	1/20/98	Chen et al.	128	782	
	$\frac{1}{C}$	5,714,978	2/3/98	Yamanaka et al.	345	157	12/5/95
	$\frac{1}{D}$	5,721,566	2/24/98	Rosenberg et al.	345	161	6/9/95
	$\frac{D}{E}$	5,724,068	3/98	Sanchez et al.	345	161	
	$\frac{E}{F}$	5,724,264	3/3/98	Rosenberg et al.	364	559	8/7/95
	$\frac{\mathbf{F}}{\mathbf{G}}$	5,727,188	3/10/98	Hayes	395	500	1/19/96
		5,731,804	3/24/98	Rosenberg	345	156	1/18/95
·	H		3/98	Rosenberg et al.	345	161	
	1 1	5,734,373		Chen et al.	345	156	11/1/95
	J	5,742,278	4/21/98		345	156	
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Information Disclosure
Statement By Applicant

(Use Several Sheets if Necessary)

Atty Docket No.
IMM1P050A
Applicant:
Martin et al.
Filing Date: 5/15/00

Group 2673

U.S. Patent Documents

			U.S. I att	t Documents		Sub-	Filing
Examiner			Data	Patentee	Class	Class	Date
Initial	No.	Patent No.	Date	Couch et al.	273	148B	5/31/95
	A	5,749,577	5/12/98		318	561	10/22/96
	В	5,754,023	5/19/98	Roston et al.	434	262	7/11/96
	C	5,755,577	5/26/98	Gillio			12/13/95
	T D	5,760,764	6/2/98	Martinelli	345	160	
	$\frac{D}{E}$	5,767,839	6/16/98	Rosenberg	345	161	3/3/95
			6/23/98	Jacobus et al.	434	262	8/10/95
	F	5,769,640	6/23/98	Jackson	345	157	7/24/95
	G	5,771,037			345	164	6/16/97
	H	5,781,172	7/14/98	Engel et al.	345	184	10/23/92
	I	5,790,108	8/4/98	Salcudean et al.			11/17/95
<u> </u>	- T	5,805,140	9/8/98	Rosenberg et al.	345	161	- 11/11/15
	K	5,818,426	10/98	Tierney et al.	345	161	

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T	Ellis, R.E. et al., "Design and Evaluation of a High-Performance Trototype Planar Haptic Interface," DSC-Vol. 49, Advances in Robotics, Mechatronics, and Haptic Interfaces, ASME 1993, pp. 55-64.
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Form 1449 (Modified)

Atty Docket No. IMM1P050A

Filing Date: 5/15/00

Serial No.: 09/571,397

Information Disclosure Statement By Applicant Applicant: Martin et al.

(Use Several Sheets if Necessary)

Group 2673

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	В	5,823,876	10/20/98	Unbehand	463		
	$\frac{1}{C}$	5,825,308	10/20/98	Rosenberg	341	20	11/26/96
			10/98	Martin et al.	318	567	
·	D	5,828,197		Rutledge	345	156	
	E	5,831,593	11/98		345	184	9/20/96
	F	5,841,428	11/24/98	Jaeger et al.			
	G	5,844,392	12/1/98	Peurach et al.	318	568.17	5/21/97
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	T	5,889,670	3/30/99	Schuler et al.	364		
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	R	Rosenberg, L. et al., "Commercially Viable Force Feedback Controller for Individuals with Neuromotor Disabilities," Crew Systems Directorate,			
		VIV. 1-14 Detterson AFR 1996 nn 1-33.			
	S	Gotow, J.K. et al., "Perception of Mechanical Properties at the Man- Machine Interface," IEEE CH2503-1, 1987, p. 688-689.			
	T	McAffee et al., "Teleoperator Subsystem/Telerobot Demonstrator. Force Reflecting Hand Controller Equipment Manual," Jet Propulsion Laboratory. California Institute of Technology, 1988, pp. 1-11.			
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	R	Russo, "The Design and Implementation of a three Degree-of-Freedom					
}		orce Output Joystick," 5/11/90, Dept. of Mech. Engineering, 1990.					
	S	Snow et al., "Compact Force-Reflecting Hand Controller," NASA Tech					
1		Brief, Vol. 15, No. 4, Item #153, 1991, pp. 1-15a.					
	T	J.N. Herndon, et al., "The State-of-the-Art Model M-2 Maintenance					
		System," 1984, 1984 Topical Meeting on Robotics and Remote Handling in					
	}	Hostile Environments, pp. 59-66.					
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